

# Performance aware open-world software in a 3-layer architecture

Diego Perez-Palacin, *Universidad de Zaragoza, Spain*

José Merseguer, *Universidad de Zaragoza, Spain*

Simona Bernardi, *Università di Torino, Italy*

# Context

- Open world software
  - Publish-subscribe; SOA; grid computing; etc.
  - Key idea: software made of services.
    - Third parties providers; interplay without authorities.
  - Performance problems
    - Are valid the current assumptions in SPE?
    - Can we trust in these third-parties?
  - Challenge
    - Self- adaptation or self-management

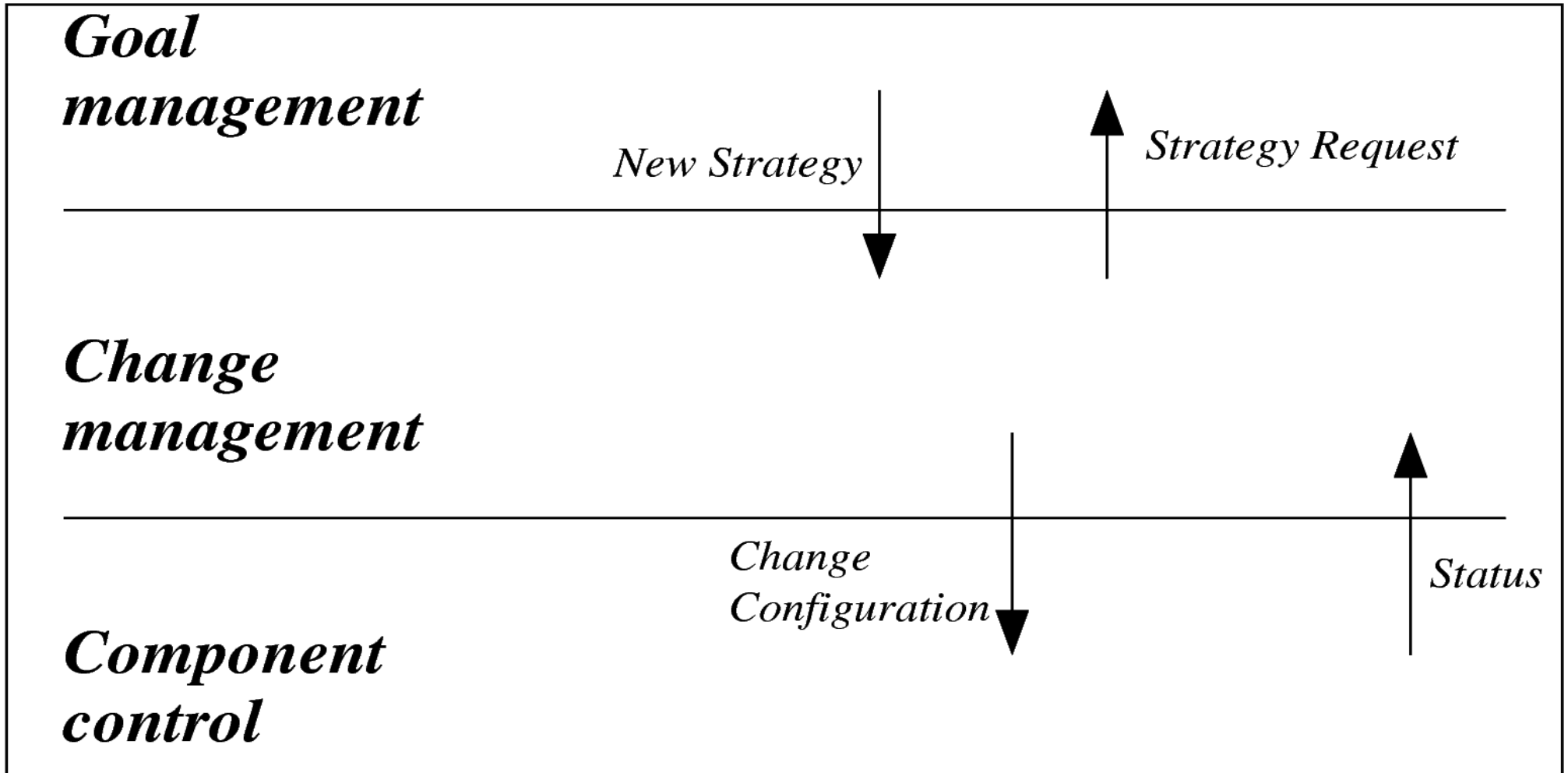
Ghezzi et al. "*Toward open world-software: Issues and challenges*", IEEE Computer 2006

# Context (2)

- Kramer & Magee proposal
  - Architecture for self- managed systems
    - Reference architecture.
    - Three layers → KM-3L
    - Benefits:
      - Scalability, abstraction, etc.
    - Inspired in autonomic systems (robotics), since they are self-managed systems.

Kramer and Magee “*Self-managed systems: an architectural challenge*”, FOSE 2007

# KM-3L





# KM-3L

- Idea
  - Identify what a self-managed system needs to carry out its mission, without human intervention.
- *Component control*
  - Carries out the system *mission*.
  - Sense environment; report *status*.
- *Change management*
  - Has the *strategy* to carry out the mission.
  - With a new *status*, executes the *strategy* to produce a new system *configuration*.
  - If the new configuration does not fulfill the mission then asks for a *new strategy*.
- *Goal management*
  - Produces strategies that satisfy the mission and consider the current configuration.

Challenge: exploit KM-3L for the open-world to incorporate performance

# KM-3L-4-OpenWorld: Component Control

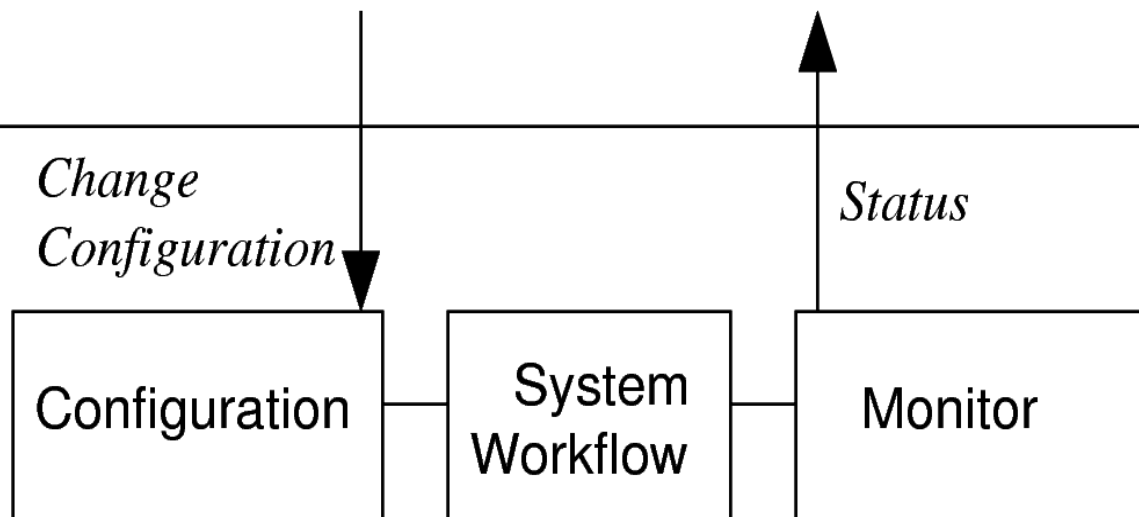
*Goal  
management*

---

*Change  
management*

---

*Component  
control*



# KM-3L-4-OpenWorld: Component Control

## ■ Responsibilities:

1. Tracking performance of components.
2. Discover new components.
3. Discover which components are no longer available.
4. Bind & unbind components.

## ■ Key: monitor module

- (1) Measure time elapsed in the service calls.
- (2,3 and 4.) As usual in open-world.

## ■ Other needs:

- Workflow (e.g., UML activity diagram)
- System configuration (e.g., UML component diagram)

## ■ Output:

- Current *status* (monitored time, unreachable service)

## ■ Input:

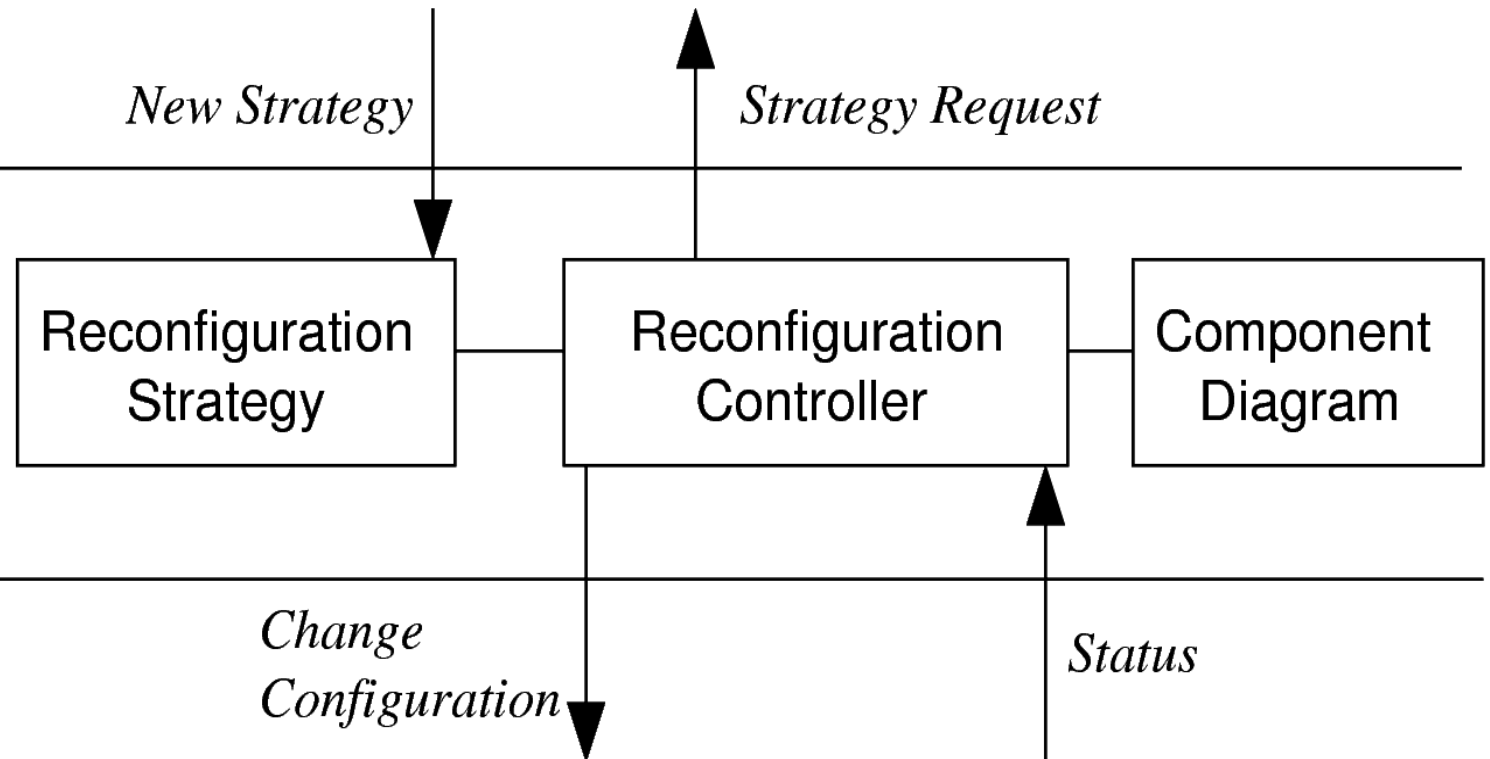
- New configuration

# KM-3L-4-OpenWorld: Change Management

*Goal  
management*

*Change  
management*

*Component  
control*



# KM-3L-4-OpenWorld: Change Management

- **Key:**

- Reconfiguration controller module.

- **Output:**

- New system configuration.

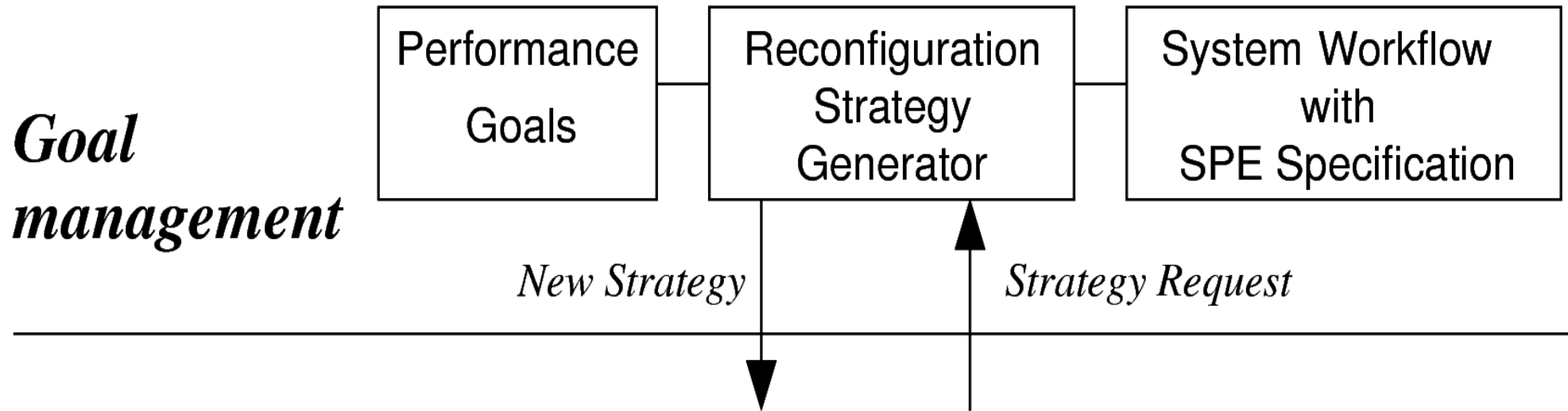
- **Input:**

- System status.
- A new strategy.

- **Actions:**

- *A component is no longer available or degraded.*
  - Executes the strategy to find a proper substitute.
  - Reports new configuration.
- A new component is available for a given service.
  - Updates the current system configuration.

# KM-3L-4-OpenWorld: Goal Management



*Change management*

---

*Component control*

# KM-3L-4-OpenWorld: Goal Management

## ■ Responsibility:

- Produce performance aware reconfiguration strategies.

## ■ Key:

- Strategy generator module.

## ■ Approaches:

- ✗ Library of strategies.
- ✓ Produce the strategy *on demand*.

## ■ Output:

- Strategy that meets the target performance goal (e.g., response time)

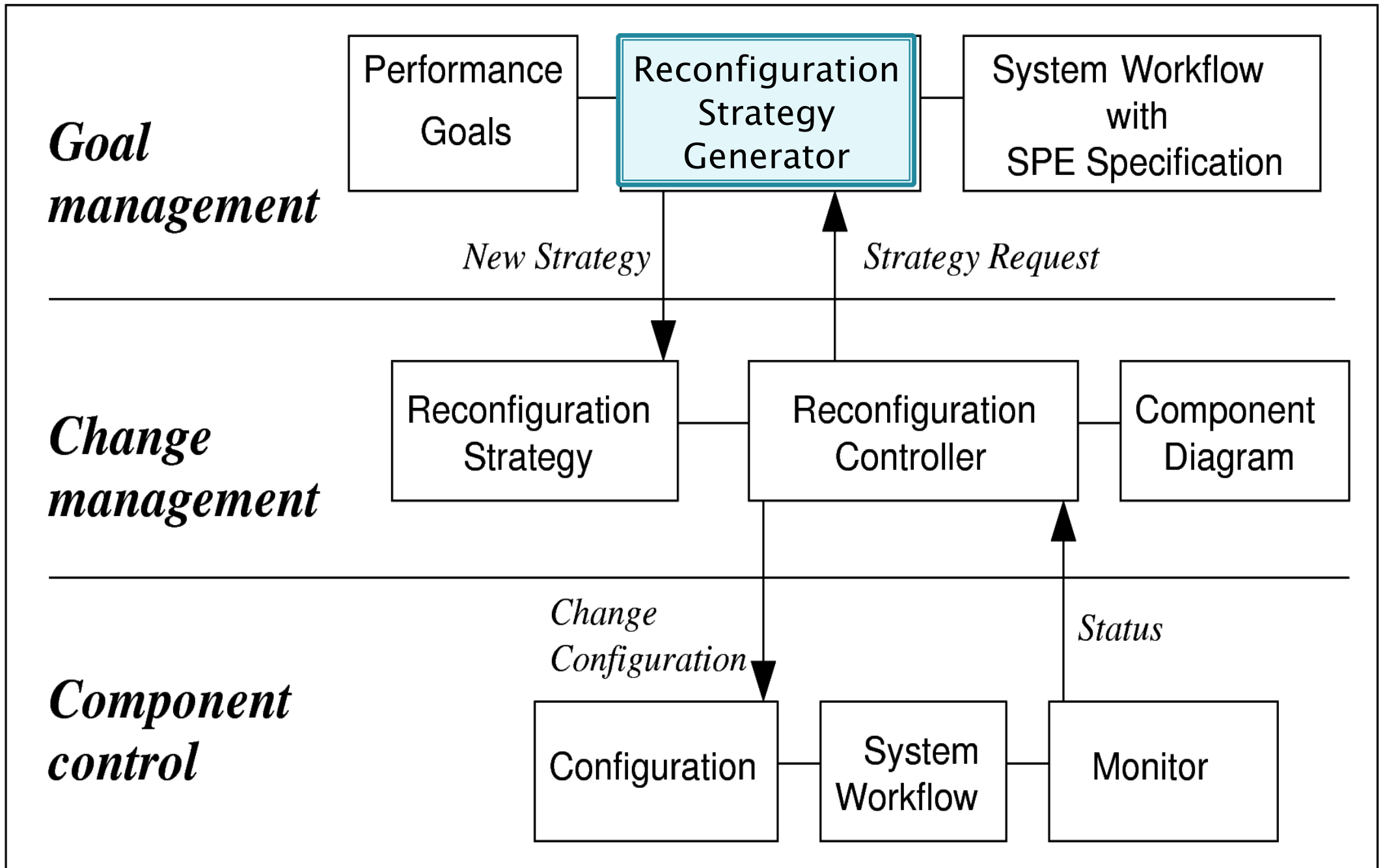
## ■ Input:

- The performance goal.
- The workflow specification.
- The current configuration.

## ■ Discussion point:

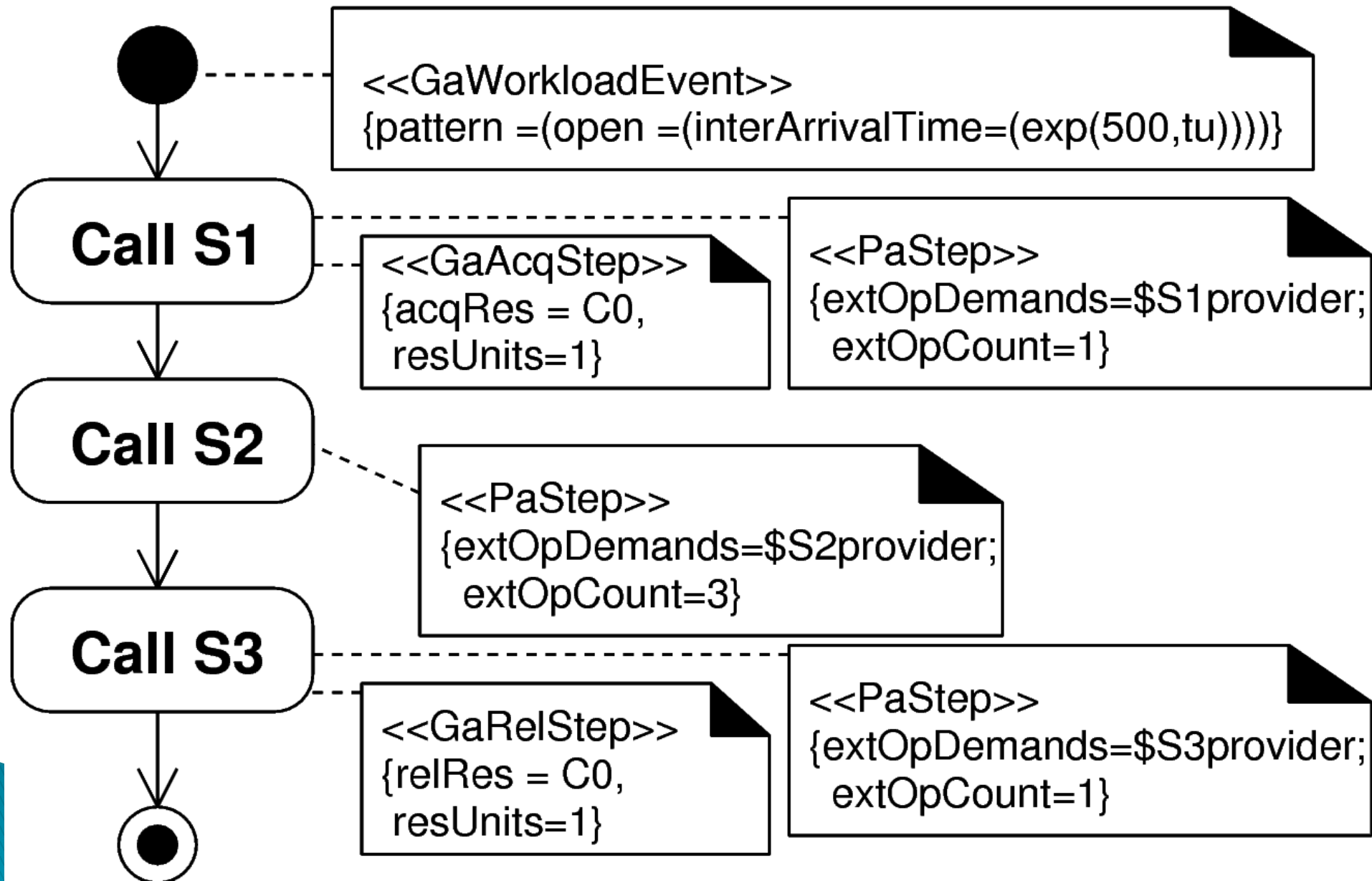
- To meet other goals (e.g., availability, price).

# KM-3L-4-OpenWorld

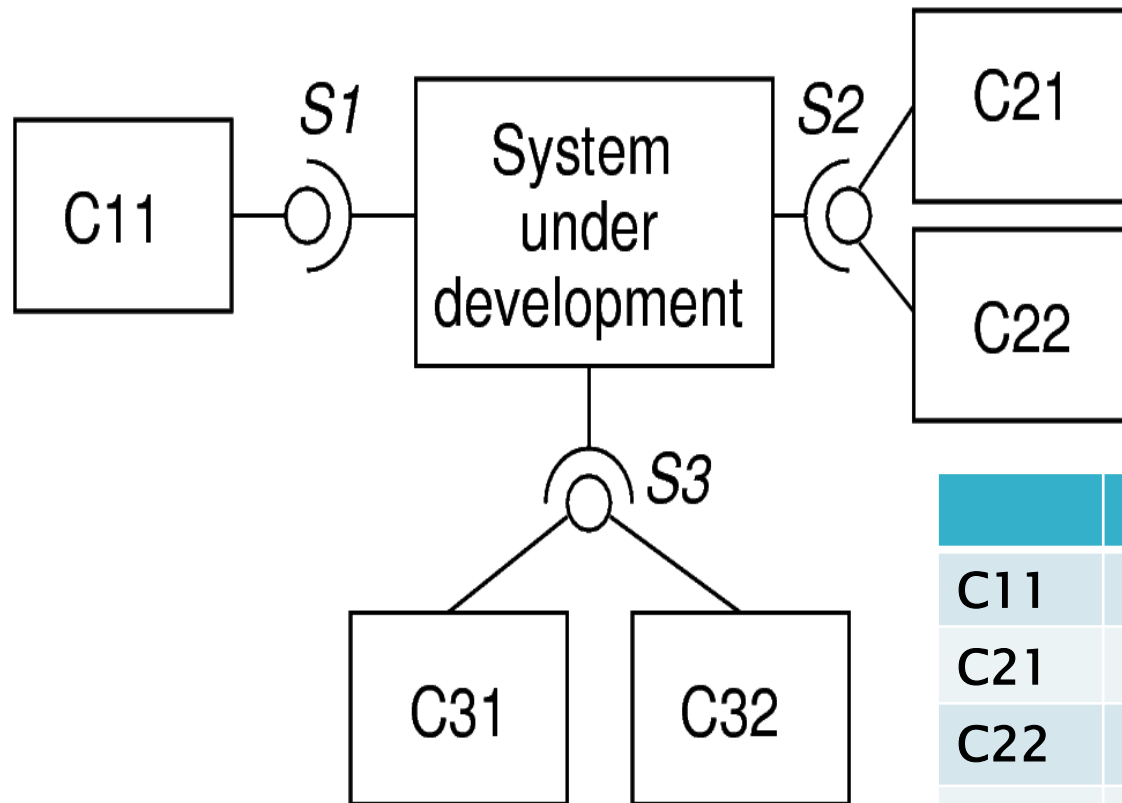




# Example (inputs)



# Example (inputs)

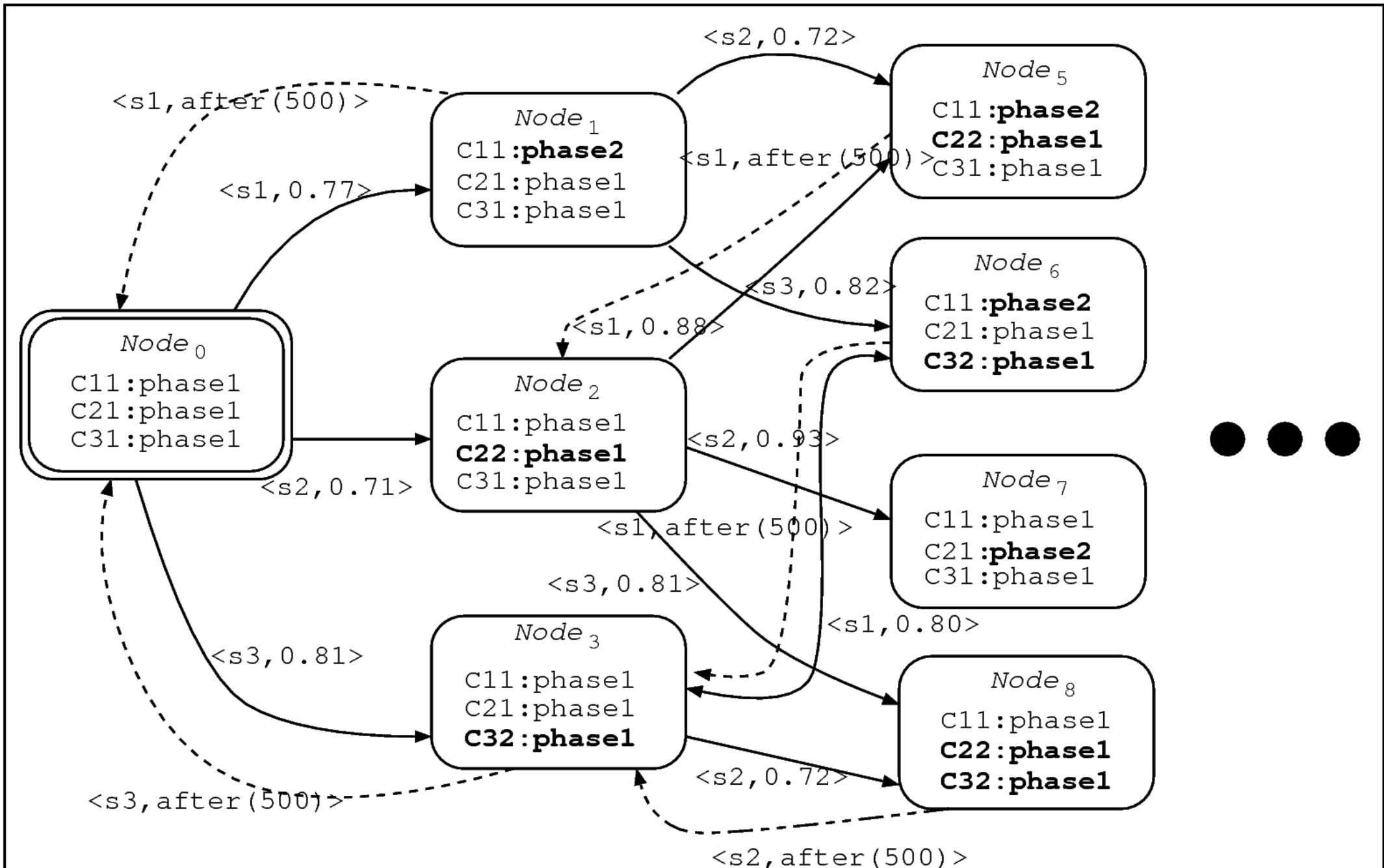


Time Table

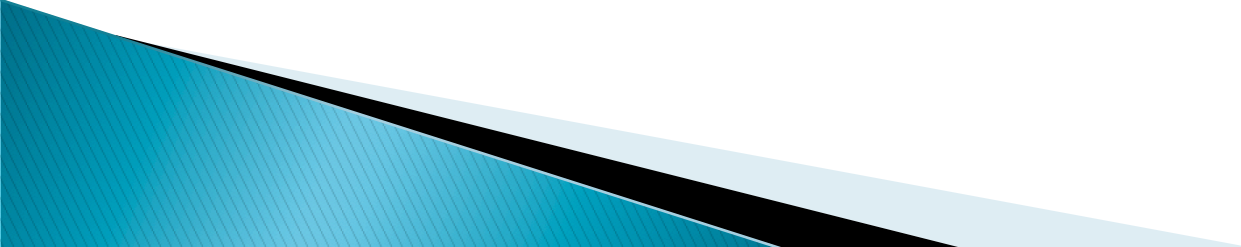
	<i>phase1</i>	<i>phase2</i>	<i>phase3</i>
C11	(5,3000)	(20,6000)	
C21	(10,6000)	(70,2000)	(250,2000)
C22	(35,6000)	(140,4000)	
C31	(20,2000)	(70,2000)	
C32	(30,∞)		

(MeanServiceTime, MeanSojournTime)

# Example (output)



# Example (strategy graph)

- ▶ Reconfiguration strategy → directed graph
  - ▶ *Nodes* are system configurations
  - ▶ *Edges* represent changes of configurations
    - *Forward* edges:
      - Replacement of a component.
      - Phase change of a component.
      - Labels → confidence levels.
    - *Backward* edges:
      - Timeouts to bring back the system to a previous configuration.
- 

# Example (1<sup>st</sup> Step: create initial node)

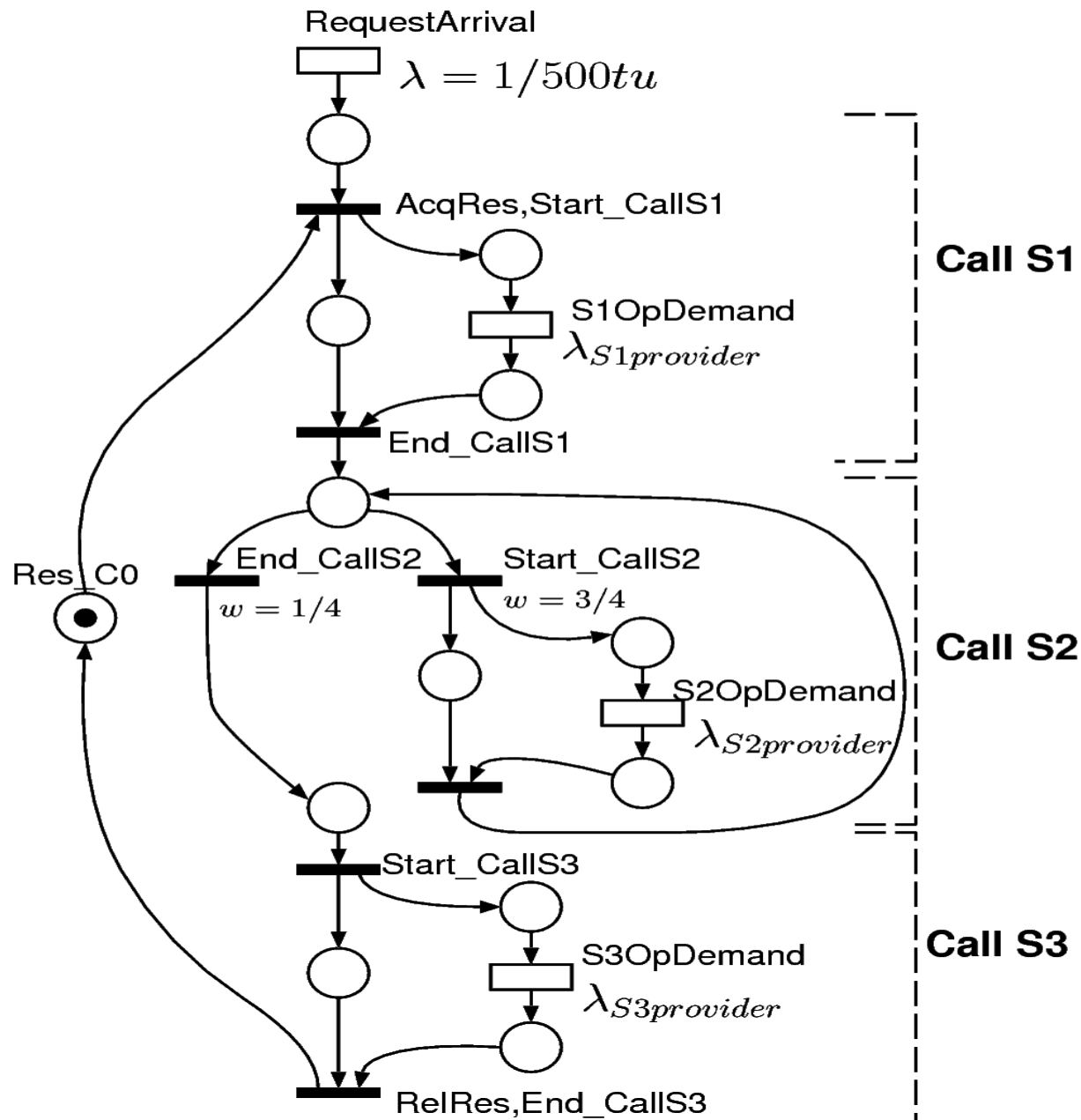
- ▶ Assume each provider works in best mode, i.e., minimum mean service time
- ▶ Four possible configurations in the example.

Mean response time estimation			
C11:ph1	C21:ph1	C31:ph1	60.5
C11:ph1	C22:ph1	C31:ph1	177.6
C11:ph1	C21:ph1	C32:ph1	72.5
C11:ph1	C22:ph1	C31:ph1	193.8

- Each configuration parameterizes the Petri net.
- Solve the Petri nets and choose the best configuration.

# Example (Petri net)

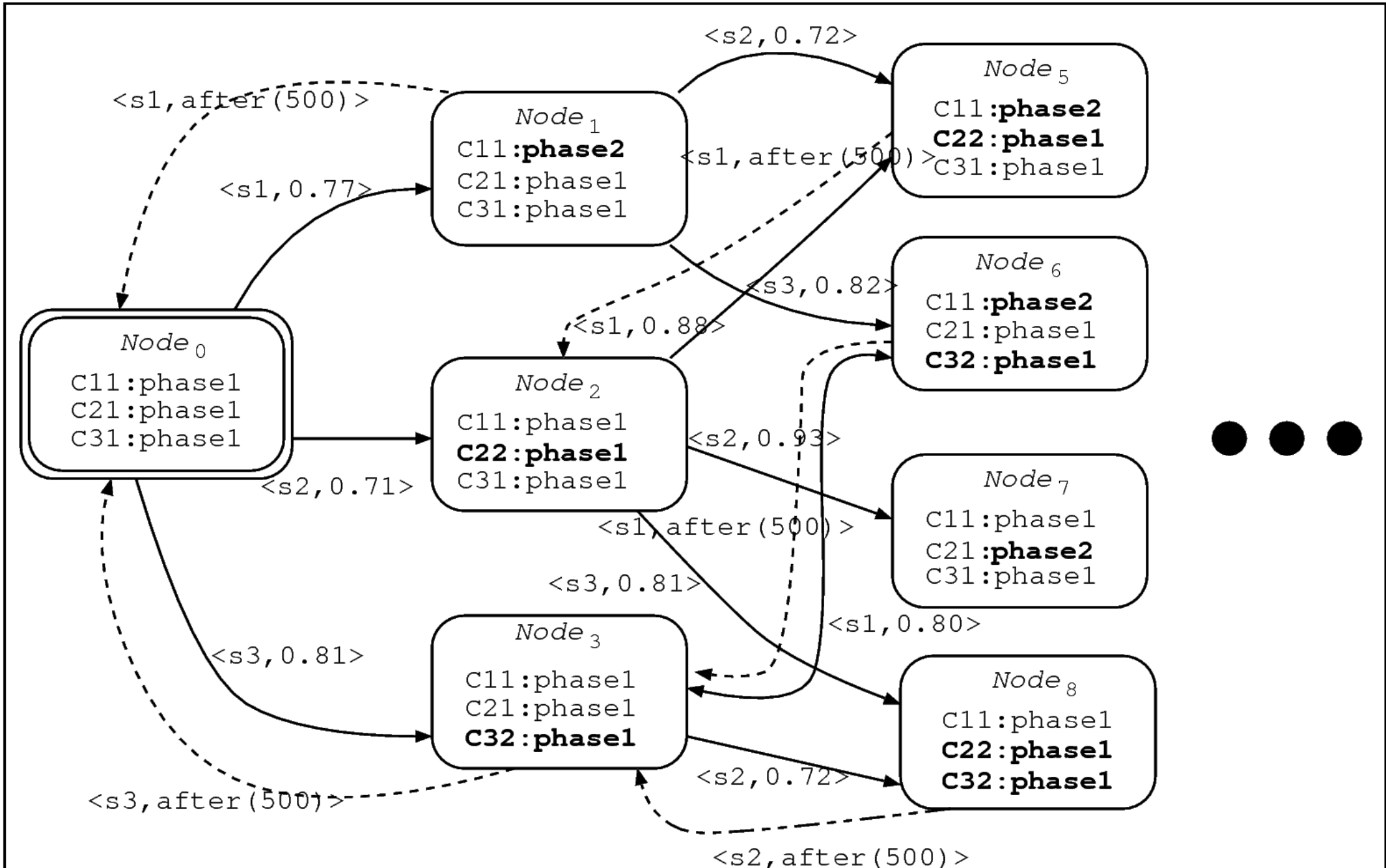
$$GSPN = (\mathcal{N}, \{\lambda_{S1provider}, \lambda_{S2provider}, \lambda_{S3provider}\})$$



# Example(2<sup>nd</sup>Step: create adjacent nodes)

- ▶ Consider that current providers can degrade their performance → 3 adjacent nodes
- ▶ **Node1** (provider one degraded)
  - No choice → only one provider
  - Solve the Petri net using *phase2* of C11.
  - Is the performance goal achieved?
- ▶ **Node2** (provider two degraded)
  - Alternatives: use C22 or C21 in *phase2*.
  - Again four possible configurations.  
Solve the Petri net.

# Example (output)





# Example(3<sup>rd</sup> Step: Labels)

- ▶ Rational:

- Our *confidence* in a configuration change.
- Ad-hoc *heuristic* under the open workload assumption.

- ▶ Confidence = Improvement/(Improvement+Lost)

- Impro

ve

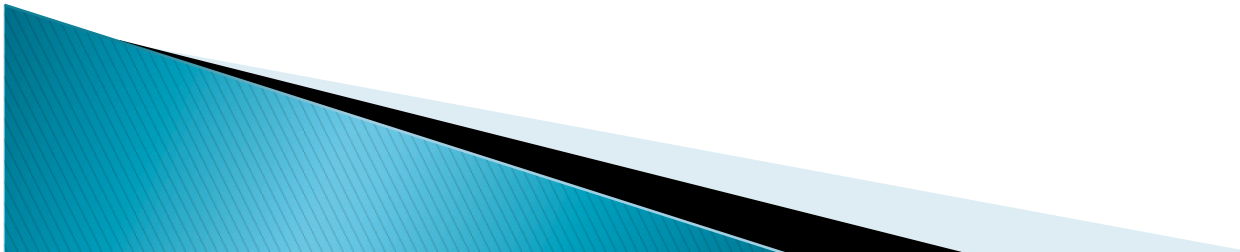
ment = RT\_source\_ch\_phase - RT\_target (*OK reconfiguration*)

- Lost = RT\_target - RT\_source (*wrong reconfiguration*)

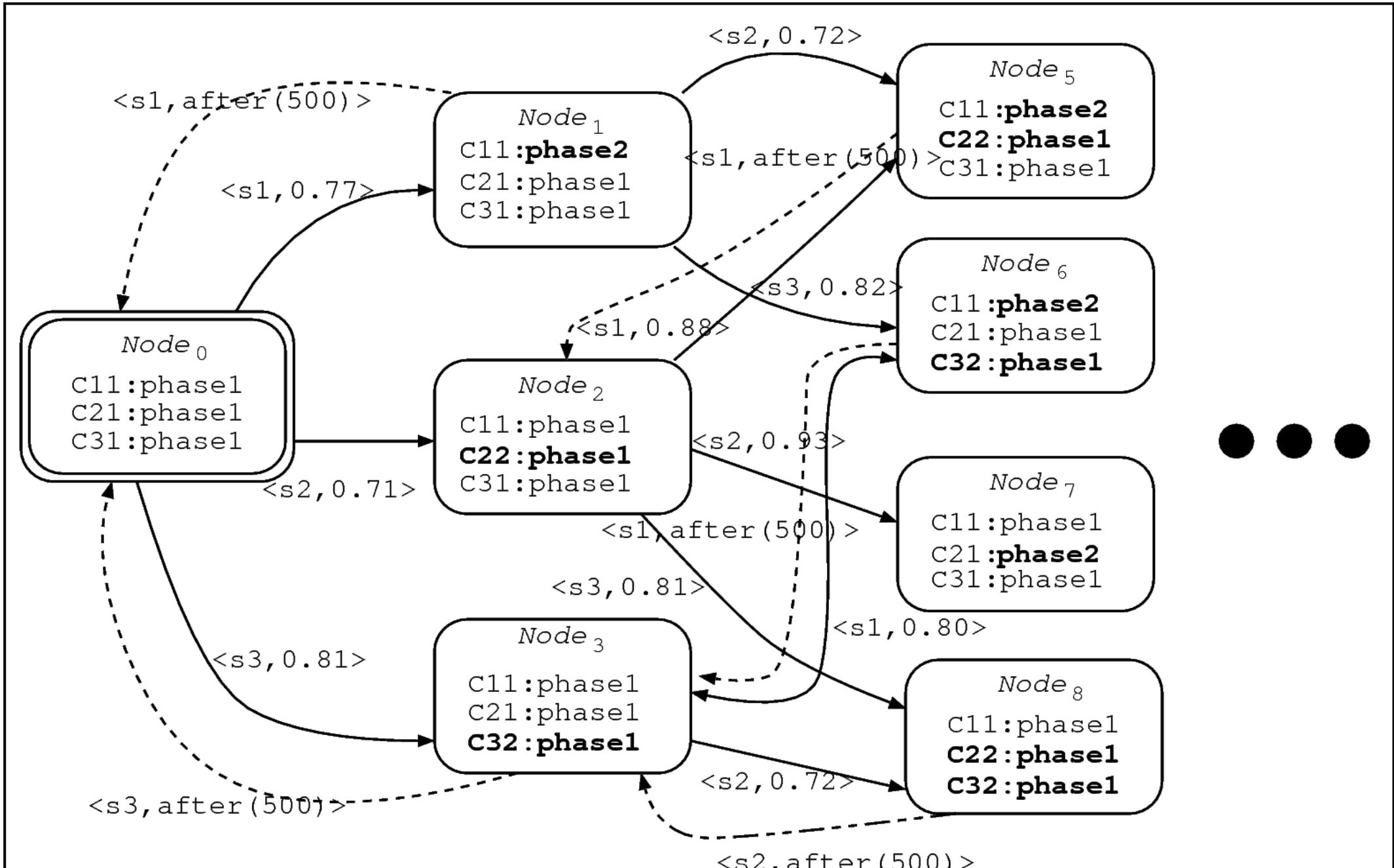
# Example (4<sup>th</sup> Step: backward edges)

## ▶ Rational

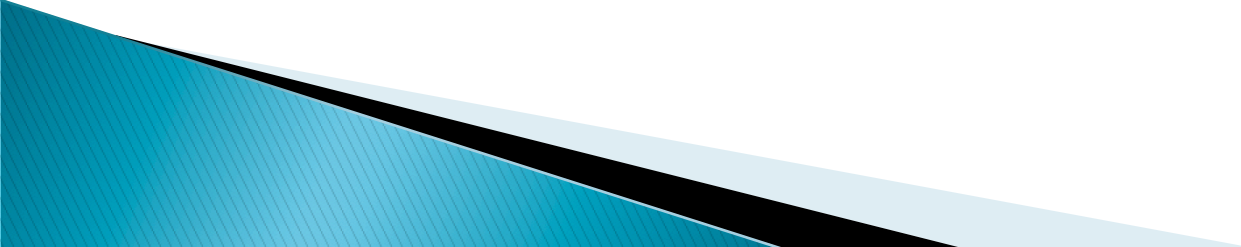
- We can perform erroneous reconfigurations.
- So, after a timeout *bring back the system* to a state that performs better:
  - Identify nodes where components perform in their worst phase.
- Ideal timeout? → Future work



# Example (output)



# Example (validation)

- ▶ We analyzed the system *without reconfigurations* and using the components with their best mean response times → Response time: *494 tu*
  - ▶ We analyzed the system *using the strategy graph* → Response time: *436 tu*
  - ▶ Improvement: *11%*
- 

# Related works

- [5] Ghezzi & Tamburrelli “Predicting performance properties for open systems with kami”, QoSA, 2009

- ✓ Performance evaluation in open-world. Assuming components evolving independently and unpredictably.
- Queuing networks.
- Does not address the problem of generate strategies.

- [10,11,15] Menascé

works (ICWS'07, Performance Evaluation'07 and WOSP'05)

- ✓ Evaluate service-based software

# Conclusion

## ■ Original idea

- Introduce a reference architecture from self-managed systems in the open-world context.

## ■ Contributions

- Adapt KM-3L to open-world software → focuss the Performance problem.
- Proposal for reconfiguration strategies module.

## ■ Challenge

- From models to real implementations → software with the ability to reconfigure itself.
- Problem → run-time Petri net evaluation with *exact analysis techniques*.
- Solution → Use Petri net *bounds*.

## ■ Final Remark

- The algorithm has been implemented.

**Thanks!**

